CLÉMENT GOSSELIN's PUBLICATIONS (updated May 2020)

Books

1. Birglen, L., Laliberté, T. and Gosselin, C., 2008, *Underactuated robotic hands*, Springer Tracts in Advanced Robotics, Vol. 40, Springer, 244 pp.

2. Kong, X. and Gosselin, C., 2007, *Type synthesis of parallel mechanisms*, Springer Tracts in Advanced Robotics, Vol. 33, Springer, 280 pp.

Articles in refereed journals

1. Wen, K. and Gosselin, C., 2020, 'Forward kinematic analysis of kinematically redundant hybrid parallel robots', to appear in the *ASME Journal of Mechanisms and Robotics*.

2. Arian, A., Isaksson, M. and Gosselin, C., 2020, 'Kinematic and dynamic analysis of a novel parallel kinematic Schnflies motion generator' *Mechanism and Machine Theory*, Vol. 147, 103629.

3. Xiang, S., Gao, H., Liu, Z. and Gosselin, C., 2020, 'Dynamic transition trajectory planning of three-dof cable-suspended parallel robots via linear time-varying MPC', *Mechanism and Machine Theory*, Vol. 146, 103715.

4. Xiang, S., Gao, H., Liu, Z. and Gosselin, C., 2020, 'Dynamic point-to-point trajectory planning for three-dof cable-suspended parallel robots using rapidly-exploring random tree search', to appear in the *ASME Journal of Mechanisms and Robotics*.

5. Tong, Z., Gosselin, C. and Jiang, H., 2020, 'Dynamic decoupling analysis and experiment based on a class of modified Gough-Stewart parallel manipulators with line orthogonality', to appear in *Mechanism and Machine Theory*.

6. Schreiber, L.-T. and Gosselin, C., 2019, 'Schönflies motion PARAllel robot (SPARA), a kinematically redundant parallel robot with unlimited rotation capabilities', *IEEE/ASME Transactions on Mechatronics*, Vol. 24, No. 5, pp. 2273–2281.

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